



# A New Transport Network Architecture with Joint Time and Wavelength Multiplexing

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# Why?

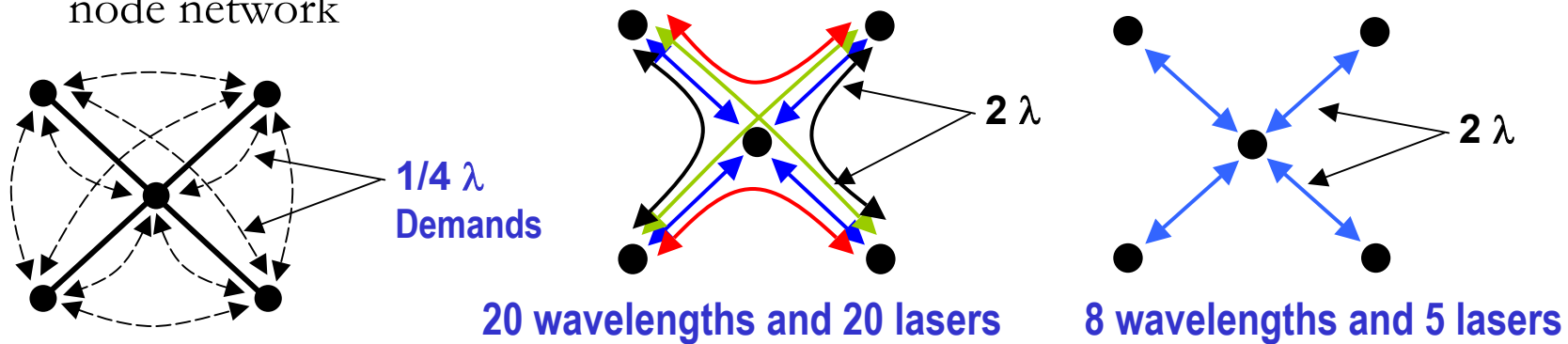
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- Per unit cost of fully utilized wavelengths ( $\lambda$ s) is low
- Applications require a very small fraction of  $\lambda$  capacity
- Effective use of  $\lambda$ s currently requires electronic grooming -- unpacking and repacking of  $\lambda$ s at most nodes
- We propose a cost-effective optical transport architecture that exploits the emerging technologies in optical transport to combine *datagram* and *circuit-switched* technologies
- The proposed architecture, TWIN,
  - Uses transport resource efficiently
  - Pushes intelligence to the (electronic) edge
  - Exploits inexpensive computational power
  - Is cost-effective, scalable, protocol agnostic
  - Has SONET-like restoration times
  - Achieves security at same level as today's circuit-switched network

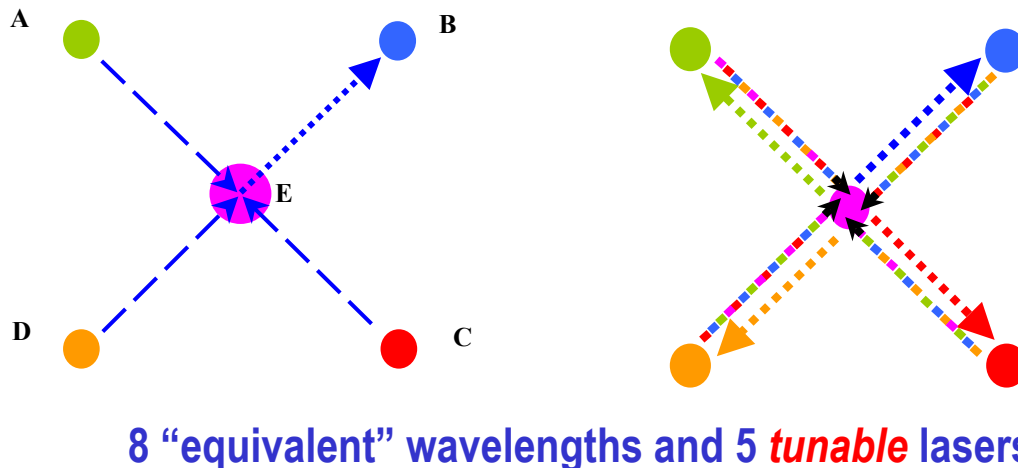


# Example: OEO, OOO & TWIN

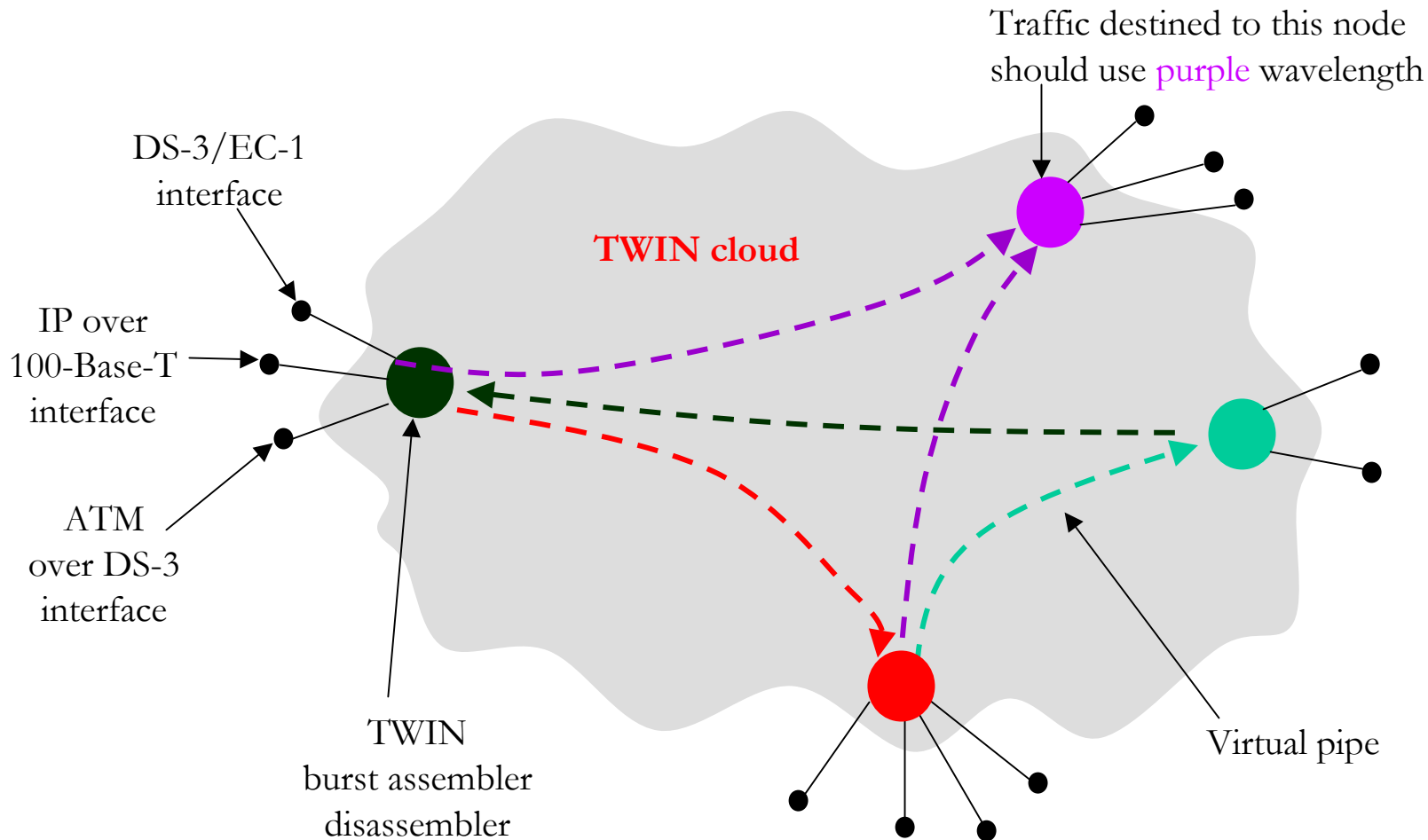
- Simple example: demands are  $1/4$  of  $\lambda$  between all node pairs in a 5 node network



- TWIN requires construction of 5 optical “wavelength trees”, with the blue tree shown below on left



# TWIN: The Network as a Switch



# Comparison of Different Architectures

| <i>Optical network architecture</i> | <i>Bandwidth efficiency</i> | <i>Core switching speed requirement</i> | <i>Optical buffering in the core</i> | <i>Data processing in the core</i> | <i>Response to dynamic traffic</i> |
|-------------------------------------|-----------------------------|---|--------------------------------------|------------------------------------|------------------------------------|
| <b>Optical Circuit Switching</b>    | Low                         | Low                                     | No                                   | No                                 | Slow                               |
| <b>Optical Burst Switching</b>      | High                        | High                                    | Possibly                             | Yes                                | Fast                               |
| <b>TWIN</b>                         | High                        | Low                                     | No                                   | No                                 | Fast                               |



# TWIN

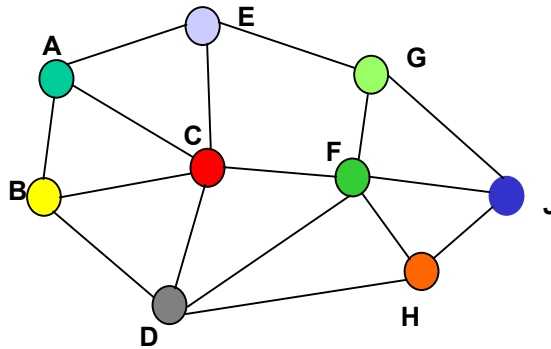
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- Architecture
- Routing
- Framing & encapsulation
- Scheduling
- Protection
- Resource discovery
- Signaling

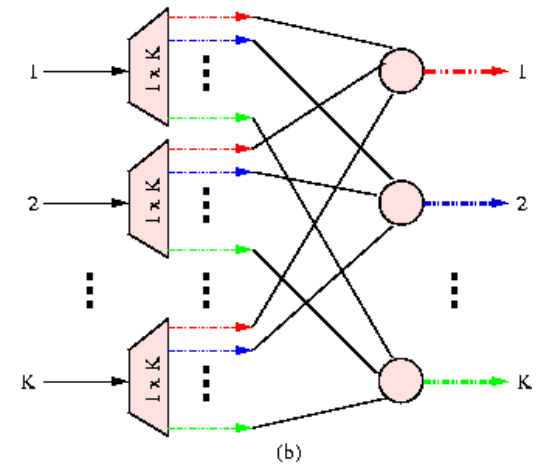
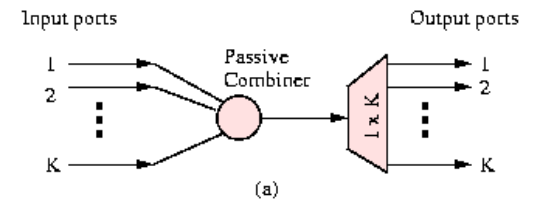


# Routing (Self-Routing) in TWIN

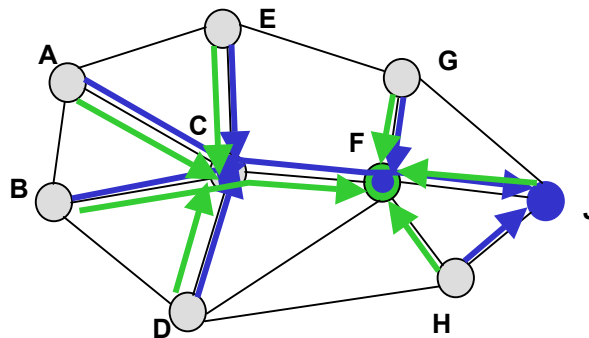
- Destination nodes have pre-assigned (set of) colors



- Pre-configured WSSs with merging ensure correct routing at intermediate nodes

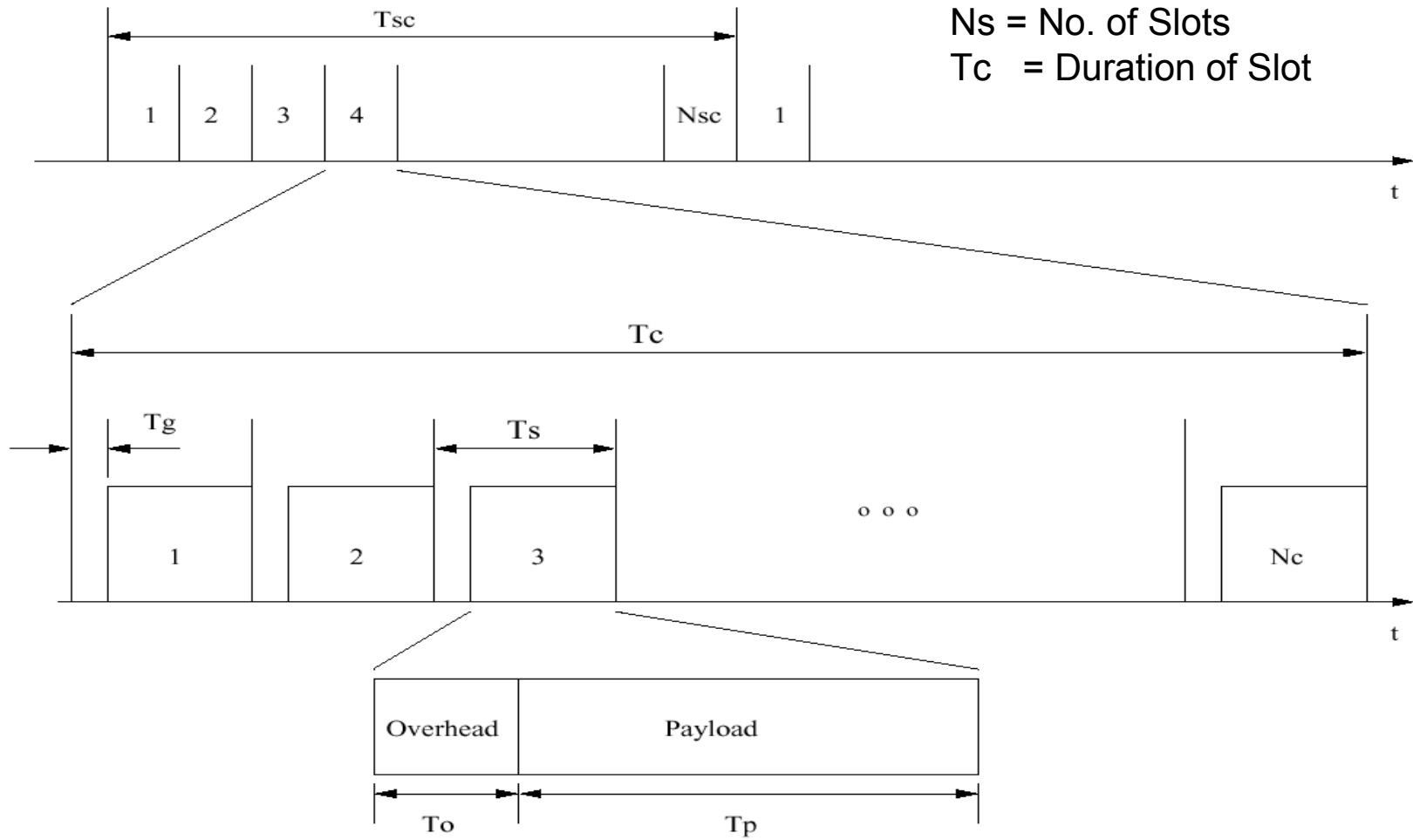


- Routing is source-based and is passive on destination trees



# Framing and Encapsulation

$T_s$  = Cycle Time  
 $N_s$  = No. of Slots  
 $T_c$  = Duration of Slot

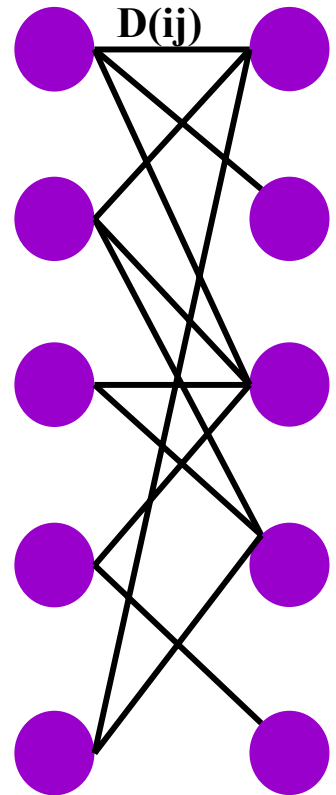




# Scheduling -- Zero Propagation Delays

Problem is matching in a bipartite graph:

- Each edge  $(i,j)$  is assigned demand  $D(i,j)$
- Edges with common input or output conflict
- A matching is a set of edges with no input or output conflict
- Select *minimal* set of matchings to cover demands
- Well-studied crossbar switch scheduling problem
  - Birkhoff-von Neumann decomposition
  - Chang, Chen, Huang (offline)
  - McKeown (online)



# Optimal Schedule

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- Minimal schedule length =

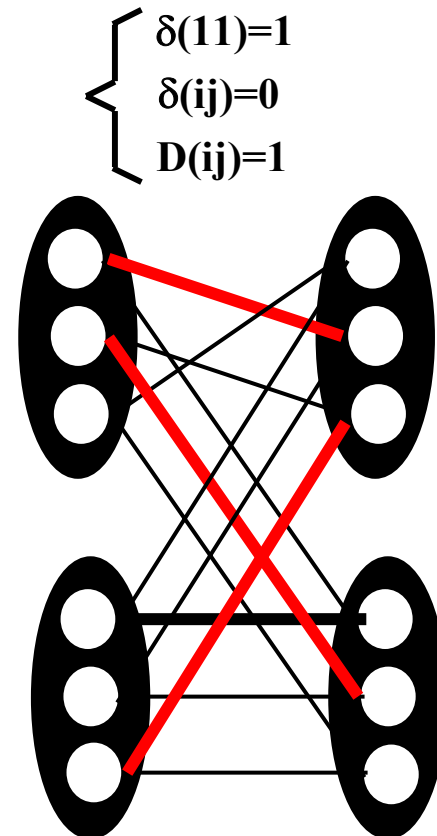
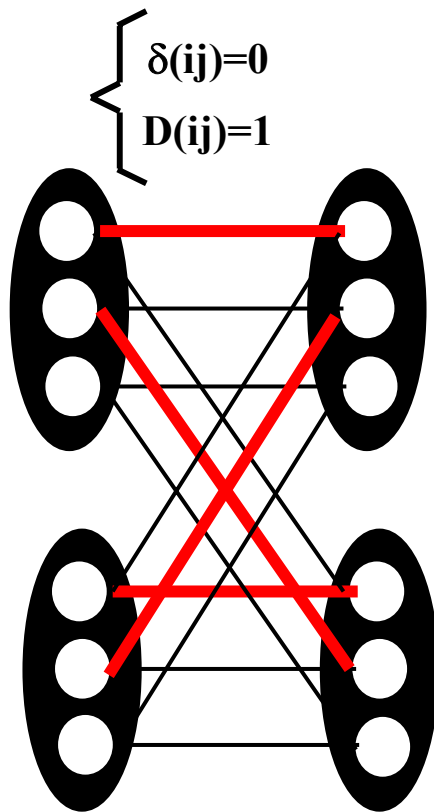
$$T^* = \max \left\{ \max_j \sum_i D(i, j), \max_i \sum_j D(i, j) \right\}$$

- Edge coloring of bipartite graphs achieves this
- TWIN scheduling is harder due to substantial propagation delays



# Matching with Propagation Delays

- Schedules without (left) and with (right) delays



# Centralized Scheduler

- Schedule for synchronous traffic via *iterative maximum independent set approximation* **TWIN Iterative Scheduler (TIS)**

Let  $D = [d_{ij}]$ .

1. Set  $S_{ij}(t) \leftarrow 0, k = 0, \dots, B - 1$

2. Set  $\hat{D} \leftarrow D$

3. Let  $(i^*, j^*, t^*) = \operatorname{argmax}_{i,j,t} \frac{f_{ij}(t)\hat{d}_{ij}}{\sum_{i',j',t' \in \Gamma_{ij}(t)} f_{i'j'}(t')\hat{d}_{i'j'}}$

4. Set  $S_{i^*j^*}(t^*) \leftarrow 1, \hat{d}_{i^*j^*} \leftarrow \hat{d}_{i^*j^*} - 1$

5. Repeat (3) until either  $f_{ij}(t) = 0$  for all  $(i, j, t)$  or  $\hat{d} = 0$ , where  $\Gamma_{ij}(t) = \{i', j, t; \forall i'\} \cup \{i, j', t' : (t - \delta_{ij}) \bmod B = (t' - \delta_{ij'}) \bmod B; \forall j'\}$ , and  $\{i, j, t\}$  denotes a burst from  $i$  is scheduled for  $j$  in slot  $t$ .



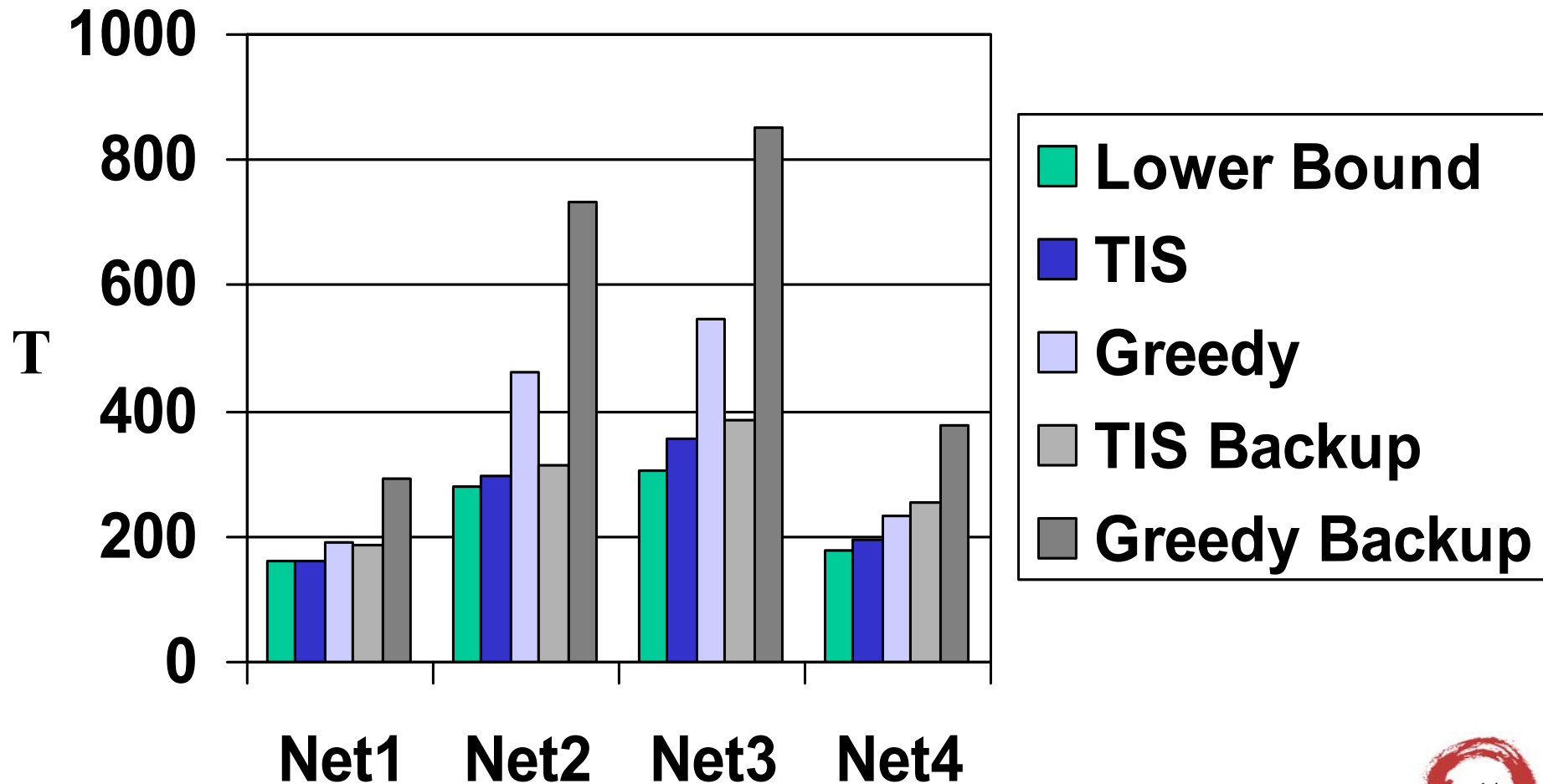
# Sample Networks

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| Network         | A                | B           | C                  | D        |
|-----------------|------------------|-------------|--------------------|----------|
| Number of nodes | 10               | 11          | 6                  | 10       |
| Distances (km)  | 150-2000         | 50-600      | 1-20               | 100-2000 |
| Demand pattern  | close to uniform | non-uniform | highly non-uniform | uniform  |



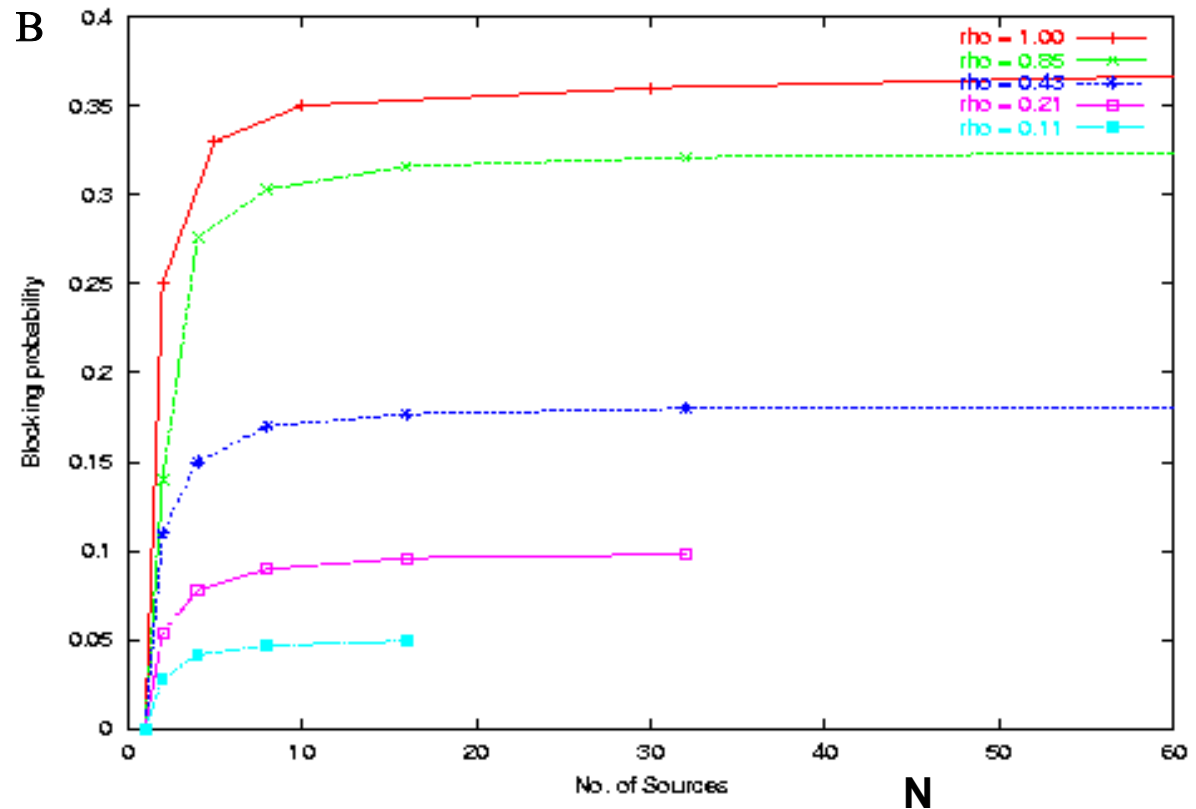
# TIS Scheduling Results



# Distributed TWIN Scheduling

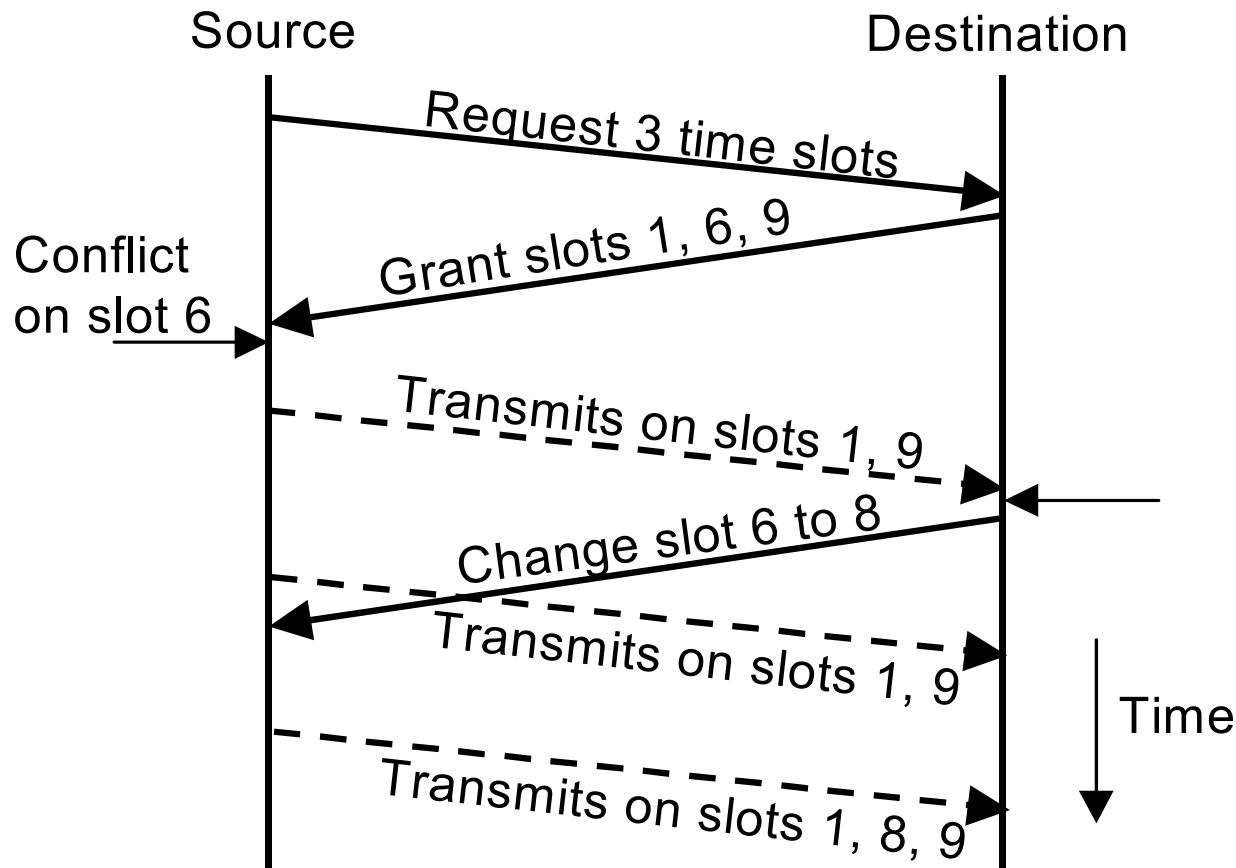
- Slotted ALOHA like Random Access Scheduler – Each node sends a batch of size  $d$  in an uncoordinated fashion

When  $Nd = 150$  (or  $\rho = 1.0$ ), observe that blocking probability is about  $B=35\%$  as  $N$  becomes large. This also corresponds to the case when a source is completely uncoordinated. Note that the blocking probability drops to about  $B=5\%$  when  $Nd = 16$  ( $\rho = 0.11$ ).



# TWIN Distributed Scheduling (TWS)

- A more intelligent distributed protocol – Destinations assign time slots based on requests to prevent collisions





# Comparison Between TIS and TWS

- Comparison between TWIN centralized and distributed schedulers

| Network             | A   | B   | C   | D   |
|---------------------|-----|-----|-----|-----|
| Lower bound $B_0^*$ | 160 | 279 | 306 | 180 |
| TIIS                | 160 | 295 | 356 | 195 |
| DS-AT               | 175 | 378 | 387 | 210 |
| DS-ATDT             | 161 | 297 | 317 | 185 |

